

# Notes on Sequence to Sequence Learning with Neural Networks

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**Abstract**

## 1 Introduction

The purpose of this document is to (i). make a few notes on [2] and (ii). fill in some of the gaps in the math that underlies the paper.

## 2 Logistic Regression

Since Sequence to Sequence Learning [2] uses two LSTMs, one for the input sequence and one for the output sequence which follow the formulation given in Graves [1]. Figure 1 shows the structure of the prediction architecture used there. More detail on the architecture of LSTM cells is shown in Figure 2 (note that this design uses the so-called "peephole connections").

Graves [1] models sequences as a multinomial distribution which can be naturally parameterized by a softmax function at the output layer. That is, if there are  $K$  text classes in total and class  $k$  is read at time  $t$ , then  $x_t$  is a  $K$  length vector which is one-hot encoded (all of its entries are zero except for the  $k^{th}$  entry which is one). Hence  $Pr(x_{t+1} = k | y_t)$  is a multinomial distribution:

$$Pr(x_{t+1} = k | y_t) = y_t^k = \frac{e^{\hat{y}_t^k}}{\sum_{k'=1}^K e^{\hat{y}_{k'}^k}} \quad (1)$$

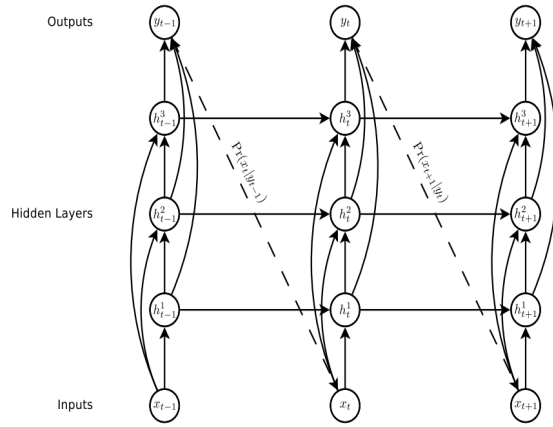


Figure 1: Deep RNN Prediction Architecture from Graves [1]

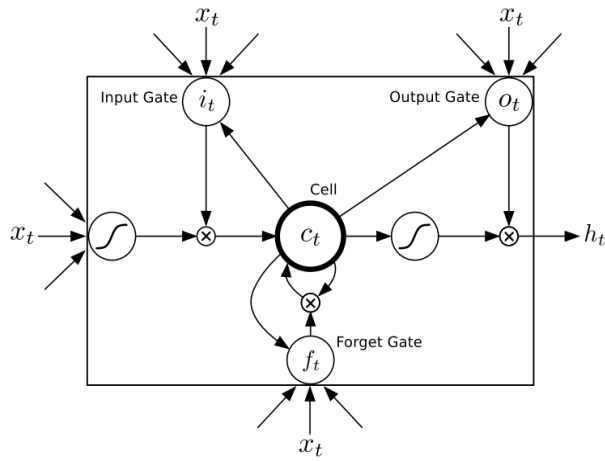


Figure 2: Long Short-Term Memory Cell

## 2.1 LSTM Activations

$$i_t = \sigma(W_{xi}x_t + W_{hi}h_{t-1} + W_{ci}c_{t-1} + b_i) \quad (2)$$

$$f_t = \sigma(W_{xf}x_t + W_{hf}h_{t-1} + W_{cf}c_{t-1} + b_f) \quad (3)$$

$$c_t = f_t c_{t-1} + i_t \tanh(W_{xc}x_t + W_{hc}h_{t-1} + b_c) \quad (4)$$

$$o_t = \sigma(W_{xo}x_t + W_{ho}h_{t-1} + W_{co}c_t + b_o) \quad (5)$$

$$h_t = o_t \tanh(c_t) \quad (6)$$

One way to understand the behavior of the multinomial distribution and its loss function  $\mathcal{L}(x)$  is to see how we compute the required gradients for logistic regression. Recall that the *logistic function*  $\sigma(x)$  is defined as follows:

$$\sigma(x) = \frac{1}{1 + e^{-x}} \quad (7)$$

We are actually interested in the derivative of  $\sigma(x)$  so that we can compute gradients for back propagation. Looking forward, note that the *softmax* classifier, which is used in [2], is defined as follows:

$$p_j = \frac{e^{o_j}}{\sum_{k=1}^K e^{o_k}} \quad (8)$$

When  $i = j$  the derivative of softmax is similar to the derivative of the logistic function, which is why it's useful to look at the logistic function.

## 2.2 Derivative of the Logistic Function

Recall the *chain rule* for derivatives is

$$\frac{d}{dx} [f(g(x))] = f'(g(x))g'(x) \quad (9)$$

Now, let the logistic function  $\sigma(x) = \frac{1}{1+e^{-x}}$ . Then for purposes of the chain rule we define

$$g(x) = 1 + e^{-x}$$

$$f(x) = \frac{1}{x}$$

so that  $\sigma(x) = f(g(x)) = \frac{1}{1+e^{-x}}$ . Taking the derivatives of  $g$  and  $f$  we get

$$g'(x) = e^{-x} \tag{10}$$

$$f'(g(x)) = (1 + e^{-x})^{-2} \tag{11}$$

Given these definitions, we have:

$$\begin{aligned} \frac{d\sigma(x)}{dx} &= \frac{d}{dx} [f(g(x))] = f'(g(x))g'(x) \\ &= \frac{e^{-x}}{(1 + e^{-x})^2} \\ &= \frac{1 + e^{-z} - 1}{(1 + e^{-z})^2} \\ &= \frac{1 + e^{-z}}{(1 + e^{-z})^2} - \left( \frac{1}{1 + e^{-z}} \right)^2 \\ &= \frac{1}{(1 + e^{-z})} - \left( \frac{1}{1 + e^{-z}} \right)^2 \\ &= \frac{1}{(1 + e^{-z})} \left( 1 - \frac{1}{(1 + e^{-z})} \right) \\ &= \sigma(x)(1 - \sigma(x)) \end{aligned}$$

This result is sometimes written as  $\frac{dy_i}{dz_i} = y_i(1 - y_i)$ .

### 3 Softmax

The following describes the derivative of the softmax function. Recall that the softmax function is defined as follows:

$$p_j = \frac{e^{o_j}}{\sum_{k=1}^K e^{o_k}}$$

When  $i = j$ , the softmax function derivative is similar to the derivative of the logistic function, namely:

$$\frac{\partial y_i}{\partial z_i} = y_i(1 - y_i) \quad (12)$$

Since [2] follows the notation and approach outlined in [1], it is useful to understand the derivation of the derivative of the loss function  $\mathcal{L}(x)$  defined there.

$$\mathcal{L}(x) = - \sum_{t=1}^T \log y_t^{x_{t+1}} \quad (13)$$

For the purposes of the derivation, we'll use

$$\mathcal{L}(x) = - \sum_j t_j \log y_i \quad (14)$$

Applying the chain rule gives us

$$\frac{\partial \mathcal{L}(x)}{\partial z_i} = - \frac{\partial \mathcal{L}(x)}{\partial y_i} \cdot \frac{\partial y_i}{\partial z_i} \quad (15)$$

Then the gradient of the loss function  $\frac{\partial \mathcal{L}(x)}{\partial z_i}$  can be derived as follows:

$$\begin{aligned} \frac{\partial \mathcal{L}(x)}{\partial z_i} &= - \frac{\partial \mathcal{L}}{\partial y_i} \left[ \sum_j t_j \cdot \log y_i \right] (y_i \cdot (1 - y_i)) \\ &= -t_j \frac{\partial \mathcal{L}}{\partial y_i} \log y_i \cdot (y_i \cdot (1 - y_i)) \\ &= -t_j \frac{1}{y_i} \cdot (y_i \cdot (1 - y_i)) \\ &= -(t_j \cdot (1 - y_i)) \\ &= y_i - t_j \end{aligned}$$

Note that  $\frac{\partial y_i}{\partial z_i}$  is replaced with  $y_i(1 - y_i)$  in the above (Section 2.2). Graves [1] uses an analogous derivation to get the following result:

$$\begin{aligned}\mathcal{L}(x) &= - \sum_{t=1}^T \log y_t^{x_t+1} \\ \implies \frac{\partial \mathcal{L}(x)}{\partial \hat{y}_t^k} &= y_t^k - \delta_{k, x_t+1}\end{aligned}\tag{16}$$

## 4 Acknowledgements

## References

- [1] Alex Graves. Generating sequences with recurrent neural networks. 08 2013.
- [2] Ilya Sutskever, Oriol Vinyals, and Quoc V. V Le. Sequence to sequence learning with neural networks. In Z. Ghahramani, M. Welling, C. Cortes, N.D. Lawrence, and K.Q. Weinberger, editors, *Advances in Neural Information Processing Systems 27*, pages 3104–3112. Curran Associates, Inc., 2014.